

Initial value problem

✓ Theorem.
Theorem:

Given $\dot{x} = Ax$ ($A \in \mathbb{R}^{n \times n}$, $x \in \mathbb{R}^n$) and $x(0) = x_0$,
then $x(t) = e^{At}x_0$

$$\boxed{\dot{x}(t)} = \frac{d}{dt}(e^{At}x_0) = \underbrace{Ae^{At}x_0}_{x(t)} = \boxed{Ax(t)}$$

Now the problem bogs down to computing e^{At}

Matrix exponential: diagonal case

$$\text{E.g. } A = \begin{bmatrix} a_1 & 0 \\ 0 & a_2 \end{bmatrix} \in \mathbb{R}^{2 \times 2}$$

$$\begin{aligned} e^{At} &= e^{At} = \mathbf{I} + (At) + \frac{1}{2!}(At)^2 + \frac{1}{3!}(At)^3 + \dots \\ &= \begin{bmatrix} 1 & \\ & 1 \end{bmatrix} + \begin{bmatrix} a_1 t & \\ & a_2 t \end{bmatrix} + \begin{bmatrix} \frac{1}{2!}(a_1 t)^2 & \\ & \frac{1}{2!}(a_2 t)^2 \end{bmatrix} + \dots \\ &= \begin{bmatrix} 1 + (a_1 t) + \frac{1}{2!}(a_1 t)^2 + \dots & \\ & 1 + (a_2 t) + \frac{1}{2!}(a_2 t)^2 + \dots \end{bmatrix} \\ &= \begin{bmatrix} e^{a_1 t} & \\ & e^{a_2 t} \end{bmatrix} \end{aligned}$$

$$x(t) = \begin{bmatrix} e^{a_1 t} & & \\ & \ddots & \\ & & e^{a_n t} \end{bmatrix} x_0$$

Matrix exponential: diagonal case

$$A = \begin{bmatrix} a_1 & & \\ & \ddots & \\ & & a_n \end{bmatrix} \in \mathbb{R}^{n \times n} \text{ diagonal}$$

$$\Rightarrow e^{At} = \begin{bmatrix} e^{a_1 t} & & \\ & \ddots & \\ & & e^{a_n t} \end{bmatrix}$$

E.g. $A = \begin{bmatrix} a_1 & \\ & a_2 \end{bmatrix}$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} \begin{matrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \\ \text{---} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \end{matrix} = \begin{bmatrix} a_1 & 0 \\ 0 & a_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$= \begin{bmatrix} a_1 x_1 \\ a_2 x_2 \end{bmatrix}$$

(decoupled)

$\dot{x}_1 = a_1 x_1$
 $\dot{x}_2 = a_2 x_2$ } two one-dim. systems

$a_1 > 0$: unstable
 $a_1 < 0$: asym. stable
 $a_1 = 0$: stable

$$\Rightarrow \begin{cases} x_1(t) = e^{a_1 t} x_{1(0)} \\ x_2(t) = e^{a_2 t} x_{2(0)} \end{cases}$$

Matrix exponential: diagonalizable case

E.g. $A = \begin{bmatrix} -1 & 1 \\ 2 & -2 \end{bmatrix}$

Idea: diagonalize A to $A_J = \begin{bmatrix} \lambda_1 & \\ & \lambda_2 \end{bmatrix}$

where λ_1, λ_2 are eigenvalues of A

and we know how to compute $e^{A_J t} = \begin{bmatrix} e^{\lambda_1 t} & \\ & e^{\lambda_2 t} \end{bmatrix}$

Find

Similarity transformation (相似变换)

Find V s.t. $V^{-1}AV = A_J$ (or $A = VA_JV^{-1}$)

A, A_J are similar

$$Av = \lambda v$$

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

$$\lambda_1 + \lambda_2 = a_{11} + a_{22} \text{ (trace)}$$

$$\lambda_1 \lambda_2 = a_{11} a_{22} - a_{12} a_{21}$$

Matrix exponential: diagonalizable case

A

$$A \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 0 = 0 \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

E.g. $A = \begin{bmatrix} -1 & 1 \\ 2 & -2 \end{bmatrix}$

$$|\lambda I - A| = 0$$

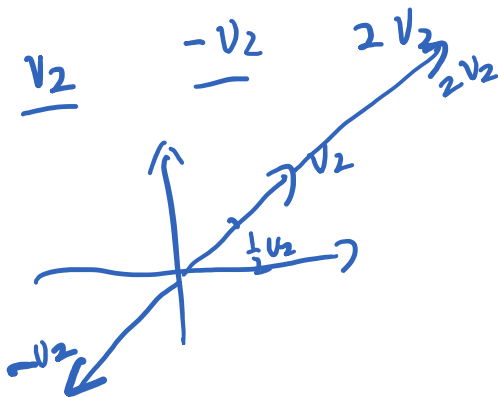
$$\begin{vmatrix} \lambda+1 & -1 \\ -2 & \lambda+2 \end{vmatrix} = (\lambda+1)(\lambda+2) - 2 = 0$$

$$\Rightarrow \lambda^2 + 3\lambda = 0$$

$$\Rightarrow \lambda(\lambda+3) = 0$$

First find eigenvalues of A: $\lambda_1 = 0$, $\lambda_2 = -3$

and the corresponding eigenvectors: $v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $v_2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$



Matrix exponential: diagonalizable case

$$\text{E.g. } A = \begin{bmatrix} -1 & 1 \\ 2 & -2 \end{bmatrix}$$

Eigenvalue-eigenvector equation:

$$\begin{aligned} Av_1 &= \lambda_1 v_1 \\ Av_2 &= \lambda_2 v_2 \end{aligned} \Rightarrow A[v_1 \ v_2] = [\lambda_1 v_1 \ \lambda_2 v_2]$$

$$\begin{aligned} &\Rightarrow A[v_1 \ v_2] = \underbrace{[v_1 \ v_2]}_V \underbrace{\begin{bmatrix} \lambda_1 & \\ & \lambda_2 \end{bmatrix}}_{A_J} \\ &\Rightarrow AV = VA_J \end{aligned}$$

$$V^{-1}AV = A_J \text{ or } A = VA_JV^{-1}$$

Matrix exponential: diagonalizable case

$$AV = \overset{AV=}{V} A_J$$

$$A^2V = \overset{A^2V=AAV}{\underline{AV}} A_J = V A_J^2$$

$$\vdots$$
$$A^kV = \overset{A^kV=}{V} A_J^k \quad (k \geq 1)$$

$$\begin{aligned} e^{At}V &= \underline{\underline{e^{At}V}} = (I + At + \frac{1}{2!}(At)^2 + \frac{1}{3!}(At)^3 + \dots)V \\ &= V + AVt + \frac{1}{2!}A^2Vt^2 + \frac{1}{3!}A^3Vt^3 + \dots \\ &\textcircled{=} V + VA_Jt + \frac{1}{2!}VA_J^2t^2 + \frac{1}{3!}VA_J^3t^3 + \dots \\ &= V(I + A_Jt + \frac{1}{2!}A_J^2t^2 + \frac{1}{3!}A_J^3t^3 + \dots) \\ &= \underline{\underline{V e^{A_J t}}} \end{aligned}$$

$e^{At} = V e^{A_J t} V^{-1}$

Matrix exponential: diagonalizable case

$$e^{At}V = Ve^{A_Jt}$$

$$\Rightarrow e^{At} = Ve^{A_Jt}V^{-1}$$

$$= [v_1 \ v_2] \begin{bmatrix} e^{\lambda_1 t} & \\ & e^{\lambda_2 t} \end{bmatrix} [v_1 \ v_2]^{-1}$$

$$= \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} e^{0t} & 0 \\ 0 & e^{-3t} \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix}^{-1}$$

$$= \dots$$

$$A = \begin{bmatrix} -1 & 1 \\ 2 & -2 \end{bmatrix}$$

$$\dot{x} = Ax$$

$$x(t) = e^{At}x_0$$

Recap

Given $\dot{x} = Ax$ ($A \in \mathbb{R}^{n \times n}$, $x \in \mathbb{R}^n$),
and suppose A is diagonalizable.

Step 1

Step 1: find eigenvalues of A : $\lambda_1, \dots, \lambda_n$
and the corresponding eigenvectors v_1, \dots, v_n

Step 2

Step 2: let $A_J := \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$, and $V := [v_1 \cdots v_n]$

compute $e^{At} = V e^{A_J t} V^{-1}$

Matrix exponential: non-diagonalizable case

Not

Not all matrices are diagonalizable

Facts:

- 1) $A \in \mathbb{R}^{n \times n}$ is diagonalizable iff A has n linearly independent eigenvectors
- 2) If A has n distinct eigenvalues, then A is diagonalizable

Matrix exponential: non-diagonalizable case

upper-triangular

E.g. $A = \begin{bmatrix} -1 & 1 \\ 0 & -1 \end{bmatrix}$

$$\lambda I - A = \begin{bmatrix} \lambda + 1 & -1 \\ 0 & \lambda + 1 \end{bmatrix}$$

$$|\lambda I - A| = (\lambda + 1)^2 = 0$$

$$\begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$$

Eigenvalues of A : $\lambda_1 = -1$, $\lambda_2 = -1$

$$\text{Left: } \begin{bmatrix} 1 & 1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$\text{R: } -1 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

But there is only one (independent) eigenvector: $v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$
(why)

So A is not diagonalizable

Matrix exponential: non-diagonalizable case

Let $M \in \mathbb{R}^{n \times n}$ be a matrix

The null space of M : $\text{null}(M) = \{v \in \mathbb{R}^n \mid Mv = 0\}$

The image space of M : $\text{image}(M) = \{v \in \mathbb{R}^n \mid (\exists v')v = Mv'\}$

Fact: $\dim(\text{null}(M)) + \dim(\text{image}(M)) = n$

So ~~dim~~^{dim}($\text{null}(M)$) = $n - \dim(\text{image}(M))$
= $n - \text{rank}(M)$

Matrix exponential: non-diagonalizable case

E.g. $A = \begin{bmatrix} -1 & 1 \\ 0 & -1 \end{bmatrix}$

Eigenvalues of A : $\lambda_1 = -1$, $\lambda_2 = -1$

But there is only one (independent) eigenvector: $v_1 =$
(why)

Eigenspace of eigenvalue -1 : $\text{null}(A - (-1)I) = \text{null}\left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right)$

$$\dim(\text{null}\left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right)) = n - \text{rank}\left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right) = 2 - 1 = 1$$

Matrix exponential: non-diagonalizable case

$$\begin{aligned} \text{E.g. } A &= \begin{bmatrix} -1 & 1 \\ 0 & -1 \end{bmatrix} \\ &= \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \end{aligned}$$

$$e^{At} = e^{\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}} t$$

Matrix exponential: non-diagonalizable case

$$e^{At} \stackrel{A_1}{=} e^{\left(\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right)t}$$

$$e^{(A_1+A_2)t} = e^{A_1 t} e^{A_2 t}$$

iff $A_1 A_2 = A_2 A_1$

$$= e^{\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} t} e^{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} t}$$

(why)

$$= \begin{bmatrix} e^{-t} & 0 \\ 0 & e^{-t} \end{bmatrix} \cdot \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} t \right) + \left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} t \right)^2 + \dots$$

$$= \begin{bmatrix} e^{-t} & 0 \\ 0 & e^{-t} \end{bmatrix} \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}$$

Matrix exponential: non-diagonalizable case

$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ is called a **nilpotent** matrix: $\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}^2 = 0$

A is nilpotent if $(\exists k \geq 1) A^k = 0$

$\begin{bmatrix} -1 & 1 \\ 0 & -1 \end{bmatrix}$ is called a **Jordan block** for -1

Matrix exponential: non-diagonalizable case

In general a Jordan block for λ is

$$A_\lambda = \begin{bmatrix} \lambda & * & & 0 \\ & \ddots & \ddots & \\ & & \ddots & * \\ 0 & & & \lambda \end{bmatrix}, \text{ where } * \text{ is } 0 \text{ or } 1$$

$$= \begin{bmatrix} \lambda & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \lambda \end{bmatrix} + \begin{bmatrix} 0 & * & & \\ & \ddots & \ddots & \\ & & \ddots & * \\ & & & 0 \end{bmatrix}$$

(λI)

$(A_{nil}: \text{nilpotent matrix})$

Matrix exponential: non-diagonalizable case

If $A = \begin{bmatrix} \lambda & 0 & & \\ & \ddots & \ddots & \\ & & \ddots & 0 \\ & & & \lambda \end{bmatrix} \in \mathbb{R}^{m \times m}$

then $e^{A\lambda t} = \begin{bmatrix} e^{\lambda t} & & \\ & \ddots & \\ & & e^{\lambda t} \end{bmatrix}$

If $\lambda < 0$

If $\lambda = 0$

If $\lambda > 0$

Matrix exponential: non-diagonalizable case

If $A_\lambda = \begin{bmatrix} \lambda & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & \lambda \end{bmatrix} \in \mathbb{R}^{m \times m}$

then $e^{A_\lambda t} = \begin{bmatrix} 1 & t & \frac{t^2}{2!} & \dots & \frac{t^{m-1}}{(m-1)!} \\ 0 & 1 & t & \dots & \frac{t^{m-2}}{(m-2)!} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & t \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix} \cdot e^{\lambda t}$

If $\lambda = 0$
 If $\lambda > 0$
 If $\lambda < 0$

Matrix exponential: non-diagonalizable case

Fact: Every matrix $A \in \mathbb{R}^{n \times n}$ has a Jordan canonical form:

similar ↗

$$A_J = \begin{bmatrix} A_{\lambda_1} & & & \\ & \ddots & & \\ & & \ddots & \\ & & & A_{\lambda_p} \end{bmatrix}$$

where $A_{\lambda_i} = \begin{bmatrix} \lambda_i & * & & \\ & \ddots & \ddots & \\ & & \ddots & * \\ & & & \lambda_i \end{bmatrix} \in \mathbb{R}^{m_i \times m_i}$ is a Jordan block

for eigenvalue λ_i with multiplicity m_i

$$(\det(sI - A)) = (s - \lambda_1)^{m_1} \cdots (s - \lambda_p)^{m_p}, \quad m_1 + \cdots + m_p = n$$